Splines vs. polynomes for fitting non-linear relationships

Brice Ozenne

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Note: this is document is inspired from http://stackoverflow.com/questions/ 15837763/b-spline-confusion

1 Simulate data

```
library(splines)
library(data.table)
library(ggplot2)
library(mgcv)
set.seed(1)
n <- 400
x <- 0:(n-1)/(n-1)
dt <- data.table(X = x,
    Ytrue = 0.2*x^11*(10*(1-x))^6+10*(10*x)^3*(1-x)^10)
dt[,Y := Ytrue + rnorm(n, 0, sd = 0.5)]</pre>
```

2 Apply spline transformation to X

```
dt[,c(X2,X3,X4,X5,X6) := .(X^2, X^3,X^4,X^5,X^6)]
SplineTempo <- bs(dt$X, knots = c(0.2, 0.5, 0.7))
dt <- cbind(dt,
    setNames(as.data.frame(SplineTempo),
    paste0("S",1:ncol(SplineTempo))))</pre>
```

3 Fit models

```
\begin{split} & \text{ImPoly} <- \mbox{Im}(Y \ \sim \ X \ + \ X2 \ + \ X3 \ + \ X4 \ + \ X5 \ + \ X6, \ data \ = \ dt) \\ & \text{ImSpline} <- \mbox{Im}(Y \ \sim \ bs(x, \ knots \ = \ c(0.2, \ 0.5, \ 0.7)), \ data \ = \ dt) \\ & \text{ImSplineI} <- \mbox{Im}(Y \ \sim \ S1 \ + \ S2 \ + \ S3 \ + \ S4 \ + \ S5 \ + \ S6, \ data \ = \ dt) \\ & \text{autoSpline} <- \ gam(Y \ \sim \ s(X), \ data \ = \ dt) \end{split}
```

Note that

range(coef(lmSpline)-coef(lmSplineI)) # same as lmSpline

[1] 0 0

Residual degree of freedom:

c(df.residual(lmPoly),df.residual(lmSpline), df.residual(autoSpline))

[1] 393.0000 393.0000 390.0559

4 Extract the fitted values

```
seqX <- seq(min(dt$X), max(dt$X), length = 100)
dt2 <- data.table(Y = dt$Y, X = dt$X, type = "observed")
predPoly <- predict(lmPoly, newdata = data.frame(X = seqX, X2 = seqX^2, X3 =
    seqX^3, X4 = seqX^4, X5 = seqX^5, X6 = seqX^6))
dt2 <- rbind(dt2, data.frame(Y = predPoly, X = seqX, type = "poly"))
predSpline <- predict(lmSpline, newdata = data.frame(x = seqX))
dt2 <- rbind(dt2, data.frame(Y = predSpline, X = seqX, type = "spline"))
predGam <- predict(autoSpline, newdata = data.frame(X = seqX))
dt2 <- rbind(dt2, data.frame(Y = predGam, X = seqX, type = "gam"))</pre>
```

5 Display fit



Splines give a better fit compared to a 3rd order polynomial when the knots are correctly placed