

penalized Latent Variable Models

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Holst

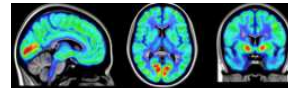
25-08-16 Compstat 2016



Motivation: depression studies

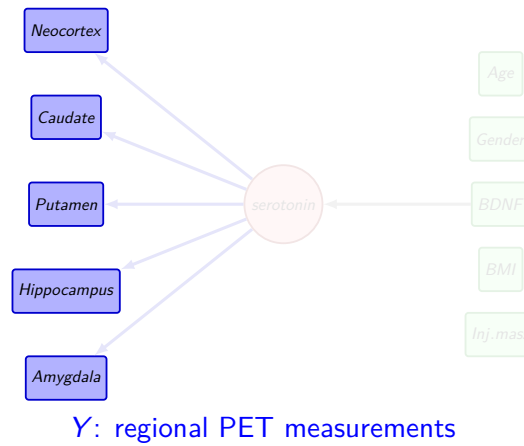
Investigate factors driving depression and response to treatment
⇒ indirect and correlated measurements

- psychological tests
 - emotional face identification
 - verbal affective memory test
- serotonin level
 - PET¹ imaging
 - average regional value
- covariates, e.g. genetic factors



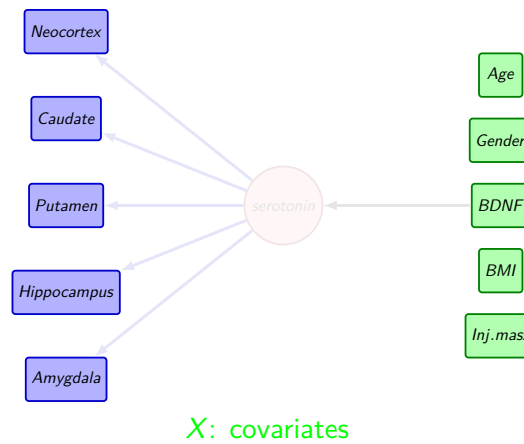
¹Positron Emission Tomography

Example of study - Fisher2014²



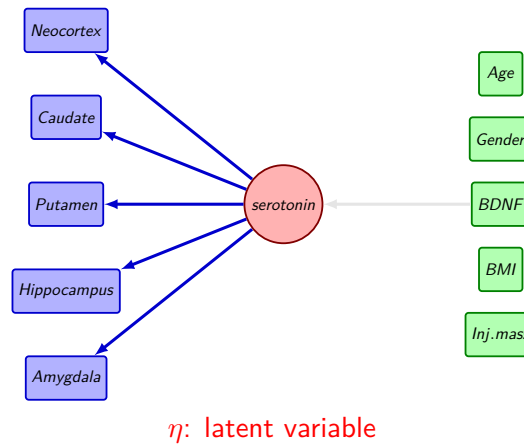
²the model presented here is a simplified version of the published model

Example of study - Fisher2014²



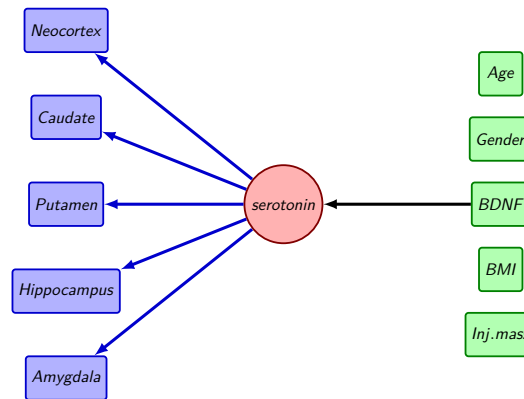
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Example of study - Fisher2014²



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Example of study - Fisher2014²



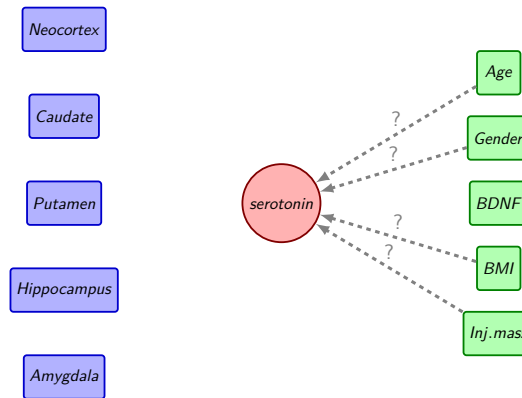
hypothesis to test

²the model presented here is a simplified version of the published model

Challenges

Causal diagram only partially known:

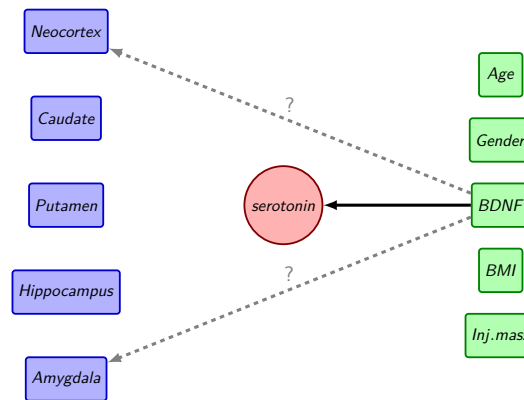
- relevant covariates
- regional specific effects



Challenges

Causal diagram only partially known:

- relevant covariates
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Challenges

Causal diagram only partially known:

- relevant covariates
 - regional specific effects
- ⇒ variable selection procedure

High-dimensional data:

- small samples (e.g. $n=73$ in **Fisher2014**)
 - images
 - large number of psychological tests
- ⇒ regularization

Different types of regularization

Favours a small number of:

- parameters

$$\mathcal{P}(\Theta) = |\Theta|_1$$

lasso
(**Tibshirani1996**)

- group of parameters

$$\mathcal{P}(\Theta) = \sum_{g=1}^G \sqrt{p^g} \|\Theta^{(g)}\|_2$$

group lasso
(**Friedman2010**)

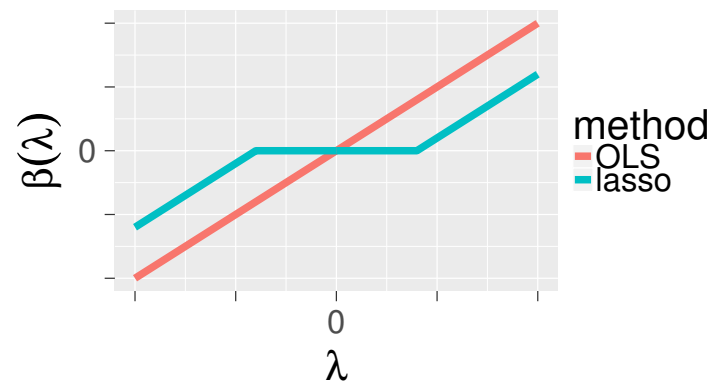
- spatial patterns

$$\mathcal{P}(\Theta) = |\text{eigen}(\Theta)|_1$$

nuclear norm
(**Zhou2014b**)

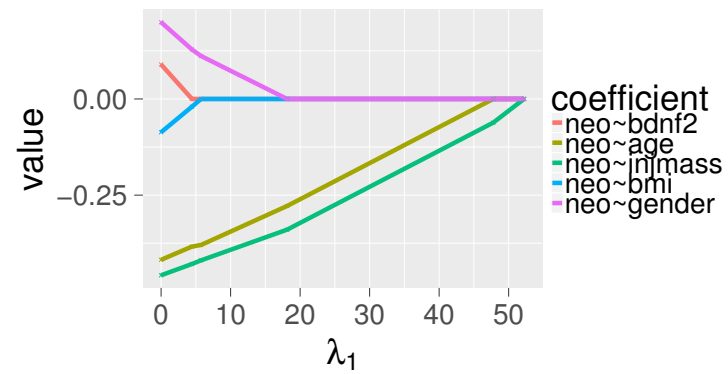
Some properties of the Lasso regression

- Orthogonal design: $\hat{\beta}_j(\lambda) = \text{sign}(Z_j)(|Z_j| - \frac{\lambda}{2})_+$, $Z = X^T Y$



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- β_j piecewise linear with λ (Efron2004)



Some properties of the Lasso regression

- Orthogonal design: $\hat{\beta}_j(\lambda) = \text{sign}(Z_j)(|Z_j| - \frac{\lambda}{2})_+$, $Z = X^T Y$
- β_j piecewise linear with λ (Efron2004)
- for suitable λ , $\mathbb{P}[\hat{S}(\lambda) = S_0] \xrightarrow{n \rightarrow \infty} 1$ (Buhlmann2011)
 S_0 true set of variables
 \hat{S} selected set of variables using lasso

Contribution

Integrate regularization into the LVM framework:

- estimation algorithm for Θ
- method for choosing the appropriate λ

$\Theta = (\beta, \sigma, \rho)$: model parameters

λ : penalisation parameter

LVM - Estimation

$$\underset{\Theta}{\operatorname{argmin}} (\mathcal{L}(\Theta))$$

where:

$$\mathcal{L}(\Theta) \propto \sum_{i=1}^n \log(|\Sigma(\Theta)|) + (Y_i - \mu_i(\Theta))^T \Sigma(\Theta)^{-1} (Y_i - \mu_i(\Theta))$$

$$\mu_i(\Theta) = \mathbb{E}[Y_i|X_i]$$

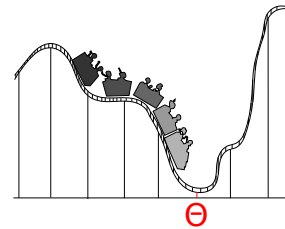
$$\Sigma(\Theta) = \mathbb{V}ar[Y_i|X_i]$$

LVM - Estimation

$$\underset{\Theta}{\operatorname{argmin}} (\mathcal{L}(\Theta))$$

Convex and differentiable likelihood:

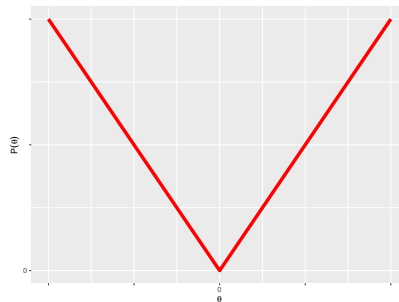
- gradient descent method
- $\Theta^i \leftarrow \Theta^{i-1} - \tau \nabla f(\Theta^{i-1})$
- quadratic convergence rate:
 $|\epsilon_{i+1}| < M \epsilon_i^2$



Estimation - penalized LVM

$$f(\Theta) = \mathcal{L}(\Theta) + \lambda \mathcal{P}(\Theta)$$

Non differentiable penalties, e.g. lasso
⇒ cannot use gradient descent methods



Proximal optimization

Proximal optimization: f convex and differentiable
 g convex but not differentiable

- x minimizes $f + g \Leftrightarrow x = \text{prox}_{\tau g}(x - \tau \nabla f(x))$

Proximal operator

- $\text{prox}_{\tau f} : \mathbb{R}^p \rightarrow \mathbb{R}^p$

$$x \mapsto \underset{v}{\operatorname{argmin}} \left(f(v) + \frac{1}{2\tau} \|v - x\|_2^2 \right)$$

e.g. $\text{prox}_{\lambda \|\cdot\|_1}(x) = \text{sign}(x)(x - \lambda)^+$

Proximal optimization

Proximal optimization: f convex and differentiable
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- x minimizes $f + g \Leftrightarrow x = \text{prox}_{\tau g}(x - \tau \nabla f(x))$

τ drives the convergence:

- $\tau \in]0; \frac{1}{L}]$, L Lipschitz constant of ∇f
 - small $\tau \equiv$ slow convergence
- \Rightarrow lower bound for $\frac{1}{L}$

Proximal gradient algorithm

```
while  $\|f(\Theta^k) - f(\Theta^{k-1})\| > \varepsilon$  do  
  Find  $\tau^k$  by backtracking  
   $\Theta^k \leftarrow \text{prox}_{\tau^k \lambda \mathcal{P}}(\Theta^{k-1} - \tau^k \nabla \mathcal{L}(\Theta^{k-1}))$   
end
```

Backtracking:

- given an initial value τ_0 and $\alpha \in]0; 1[$
- find the first $\tau = \tau_0 \alpha^i, i \in \{0, 1, \dots\}$ satisfying:

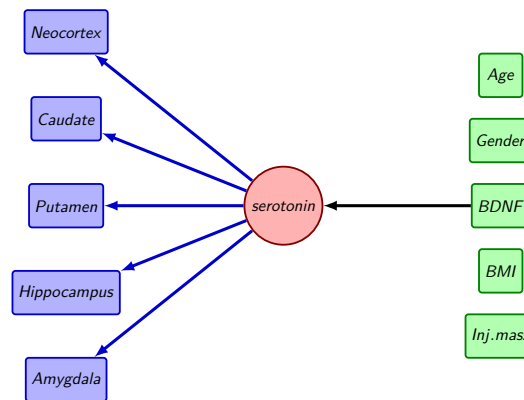
$$f(\Theta_\tau^k) \leq f(\Theta^{k-1}) + \nabla f(\Theta_\tau^k)^\top (\Theta^{k-1} - \Theta_\tau^k) + \frac{1}{2\tau} \|\Theta^{k-1} - \Theta_\tau^k\|_2^2$$

We will have $\hat{\tau} \geq \min(\tau_0, \frac{\alpha}{L})$

Back to our application

Lasso LVM: *mispecified model !*

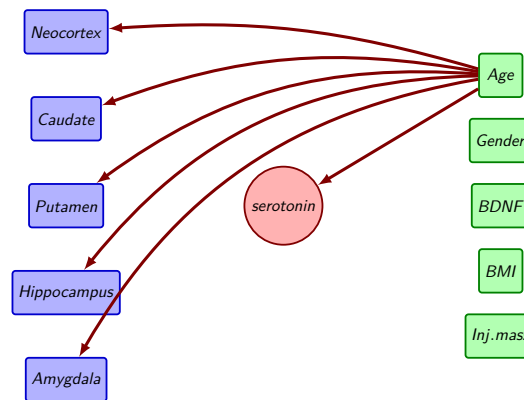
- penalize all links except those chosen a priori



Back to our application

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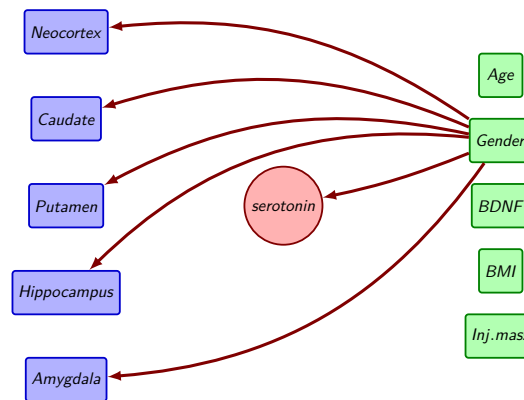
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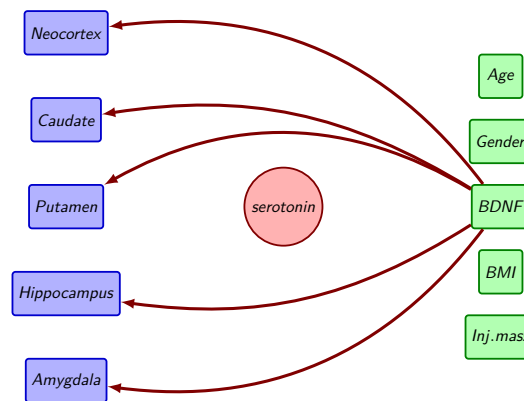
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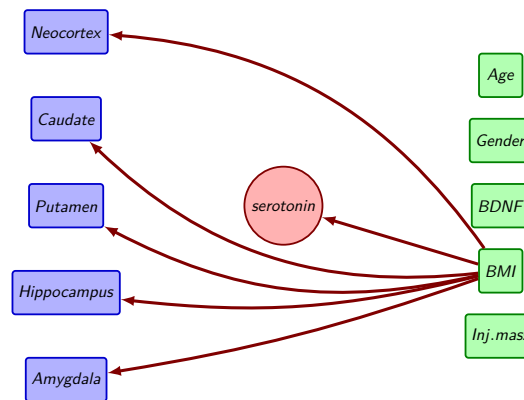
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Lasso LVM: *mispecified model !*

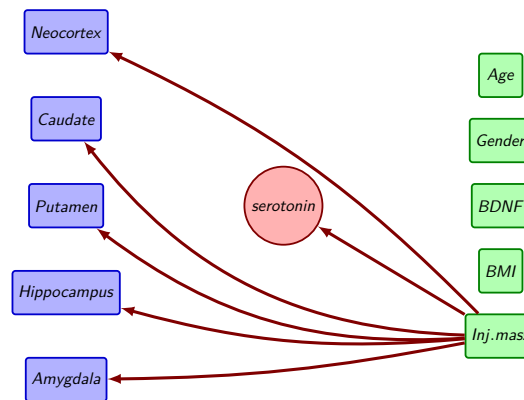
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Lasso LVM: *mispecified model* !

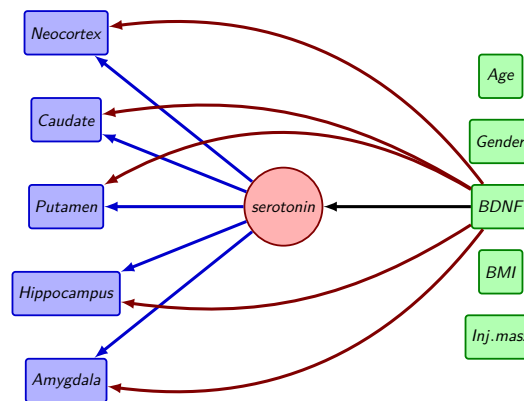
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Lasso LVM: misspecified model !

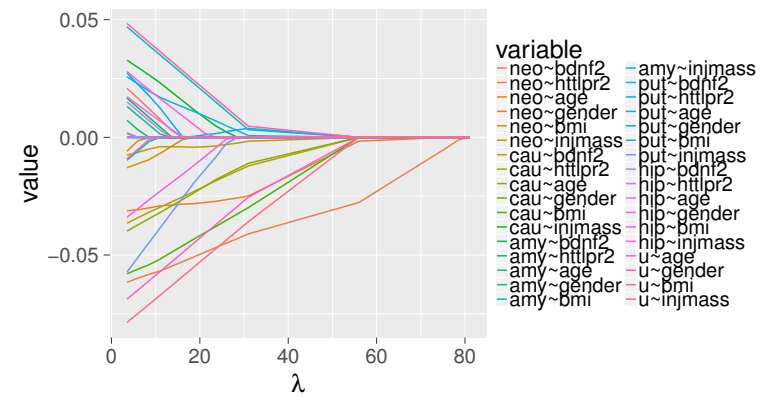
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Back to our application

Variable selection procedure:

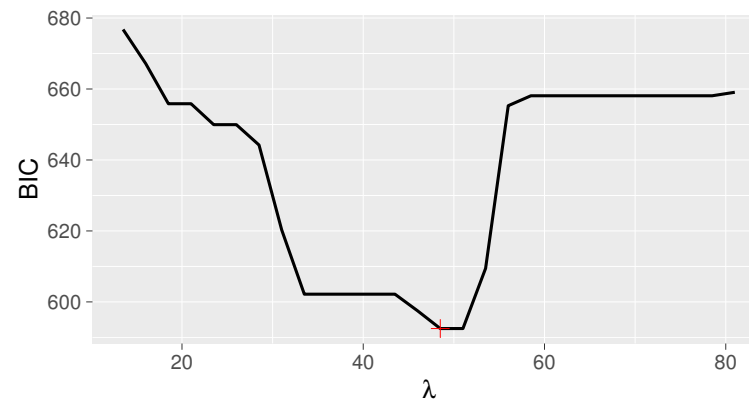
- grid search over λ
- optimal model according to the BIC



Back to our application

Variable selection procedure:

- grid search over λ
- optimal model according to the BIC



Simulation study

Match lasso regression estimations

- low dimensional case
- high dimensional case

Convergence of lasso LVM

- low dimensional case: ok
- high dimensional case: ok if λ is high enough

Variable selection with lasso LVM

- conservative method

Choosing λ

Limitation of grid search

- may miss interesting λ
- time consuming

Regularization path

- set of λ where the set of non 0 coefficients changes
⇒ called "breakpoints"
- likely to be the set of relevant λ

EPSODE algorithm

- (**Zhou2014a**) proposed a generalization of LARS to convex functions
⇒ applicable to LVM ?

Penalization path for LVM

$$\frac{\partial \Theta}{\partial \lambda} = ?$$

Penalization path for LVM

$$f_\lambda(\Theta) = \mathcal{L}(\Theta) + \lambda \|\Theta\|_1 = \mathcal{L}(\Theta) + \lambda(\Theta^+ + \Theta^0 - \Theta^-)$$

For a small $d\lambda$:

$$\begin{aligned} & \operatorname{argmin}_{d\Theta} (f_{\lambda+d\lambda}(\Theta + d\Theta) - f_\lambda(\Theta)) \\ &= \operatorname{argmin}_{d\Theta, \eta} \left(\nabla \mathcal{L}(\Theta) d\Theta + \frac{1}{2} \nabla^2 \mathcal{L}(\Theta) (d\Theta)^2 + o((d\Theta)^2) \right. \\ & \quad \left. + (\lambda + d\lambda)(d\Theta^+ + d\Theta^-) + \eta d\Theta^0 \right), \eta \text{ lagrange multiplier} \\ &= \dots \end{aligned}$$

So

$$\frac{d\Theta}{d\lambda} = -P(\nabla^2 \mathcal{L}(\Theta), \operatorname{sign}(\Theta)) u_z(\operatorname{sign}(\Theta))$$

Estimation - Penalization path

$$\frac{d\Theta}{d\lambda} = -P(\nabla^2 \mathcal{L}(\Theta), \text{sign}(\Theta)) u_z(\text{sign}(\Theta))$$

P matrix

u_z vector

Linear regression:

- $\nabla^2 \mathcal{L}(\Theta)$ piecewise constant
- ⇒ P piecewise constant (**Efron2004** - LARS)

Estimation - Penalization path

$$\frac{d\Theta}{d\lambda} = -P(\nabla^2\mathcal{L}(\Theta), \text{sign}(\Theta))u_z(\text{sign}(\Theta))$$

P matrix

u_z vector

LVM:

- $\nabla^2\mathcal{L}(\Theta)$ not constant

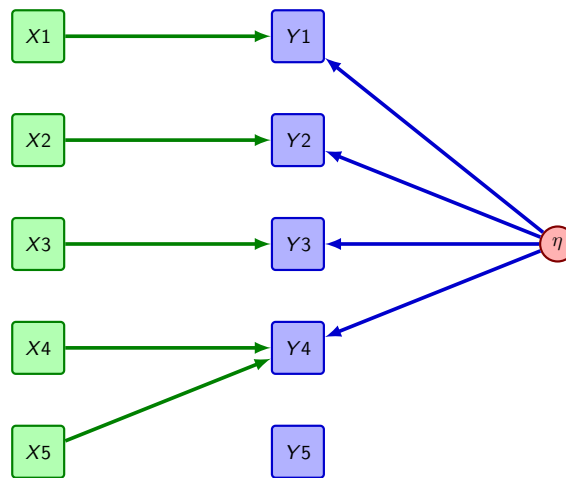
⇒ Solve differential equation

Assumption: $\nabla^2\mathcal{L}(\Theta)$ constant between two discretization points

TRUE Model

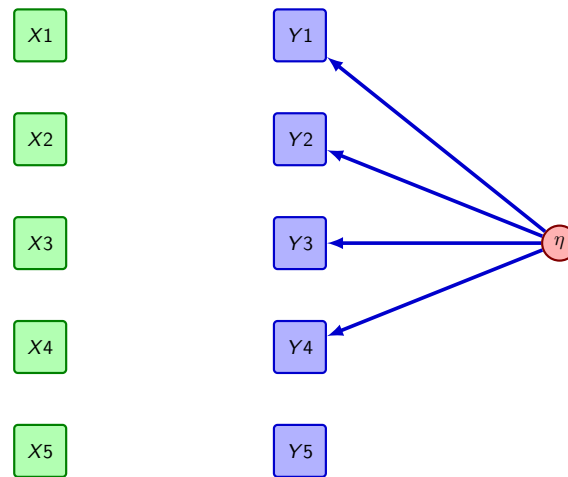
$Y_i \sim \mathcal{N}(0, 1)$

$n = 500$



pLVM containing the TRUE model

All links are penalized except those shown below:

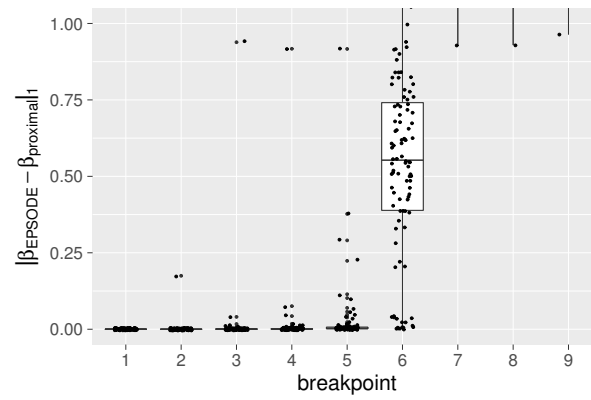


Simulation study

For each sample:

- Simulate data according to the TRUE model
- Estimate the breakpoints for the pLVM using EPSODE:
→ $\{\lambda_1, \dots, \lambda_p\}$
- Keep the coefficients of the pLVM estimated by EPSODE
→ β_{EPSODE}
- Proximal gradient for the pLVM applied at $\{\lambda_1, \dots, \lambda_p\}$
→ $\beta_{proxGrad}$
- agreement: $\sum_{j=1}^p |\beta_{proxGrad,j} - \beta_{EPSODE,j}|$

Accuracy of the regularization path



⇒ incorrect after a number of breakpoints (here 5)

Summary

Integration of regularization into LVM:

- proximal gradient
- lasso, ridge, elastic net, group lasso penalty
- nuclear norm

⇒ user-specific penalty terms can be used specifying the proximal operator

Regularization path:

- lasso, ridge, elastic net
- increasing bias along the path
 - need explicit formulation for the hessian ?
 - need thinner mesh ?

Perspectives

- nuclear norm penalty ($n=500, p=4096+5$)

